

CIV102: Finals Review

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1 Trust

- To be a safe bridge, we want to prevent tension/compression failure by demanding the cross sectional area be:

$$A \geq \frac{2F}{\sigma_y} \quad (1)$$

where σ_y is the yield strength and for steel, it is the same for both compression and tension.

- To prevent compression members from buckling, the moment of inertia needs to be:

$$I \geq \frac{3FL^2}{\pi^2 E} \quad (2)$$

- And we also demand the radius of gyration r to be:

$$r \geq \frac{L}{200} \quad (3)$$

- To use the method of virtual work, replace all applied forces with a single force F^* at the location of interest and solve for the forces in all the members P^* . Then the displacement is:

$$\Delta = \frac{1}{F^*} \sum \frac{PP^*L}{AE} \quad (4)$$

- For a point load at midspan, the frequency of oscillations is:

$$f_n = \frac{15.76}{\sqrt{\Delta}} \quad (5)$$

For a uniformly distributed load, we have:

$$f_n = \frac{17.76}{\sqrt{\Delta}} \quad (6)$$

2 Beam

- Navier's equation is:

$$\sigma = \frac{My}{I} \quad (7)$$

- The curvature is:

$$\phi = \frac{M}{EI} \quad (8)$$

- The change in slope between two points is given by the **first moment area theorem**:

$$\Delta_{AB} = \theta_B - \theta_A = \int_A^B \phi(x) dx \quad (9)$$

- The **second moment area theorem** gives the deviation of point D from the tangent drawn at point T as:

$$\delta_{DT} = \int_D^T x\phi(x) dx = \bar{x}_{DT} \int_D^T \phi(x) dx = \sum \bar{x} \int \phi(x) dx \quad (10)$$

- There are three scenarios when finding the deflection:
 - Known horizontal tangent due to support: Find the deflection of the point of interest from the support condition.
 - Known horizontal tangent due to symmetry: Find the deflection of the support from the point of interest.
 - No known horizontal tangents: Find the deflection of support C from the tangent drawn from the other support A . Find the deflection of the point of interest from support A . Use similar triangles to relate them together. To calculate the deflection of the support from A , we have:

$$\theta_A = \frac{\delta_{CA}}{L} \quad (11)$$

- Shear stresses are given by **Jourawski's equation**:

$$\tau = \frac{VQ}{Ib} \quad (12)$$

where:

$$Q = \int_{y_{bot}}^y y dA = \int_y^{y_{top}} y dA = \sum Ad \quad (13)$$

- Plate buckling equations are given below:

Table 30.2 – Summary of plate buckling failure modes

No.	Failure Mode	Failure Condition	Relevant Design Equation
5	Buckling of the compressive flange between the webs	$\sigma = \frac{4\pi^2 E}{12(1-\mu^2)} \left(\frac{t}{b}\right)^2$	$\sigma = \frac{My}{I}$
6	Buckling of the tips of the compressive flange	$\sigma = \frac{0.425\pi^2 E}{12(1-\mu^2)} \left(\frac{t}{b}\right)^2$	
7	Buckling of the webs due to the flexural stresses	$\sigma = \frac{6\pi^2 E}{12(1-\mu^2)} \left(\frac{t}{b}\right)^2$	
8	Shear buckling of the webs	$\tau = \frac{5\pi^2 E}{12(1-\mu^2)} \left(\left(\frac{t}{h}\right)^2 + \left(\frac{t}{a}\right)^2 \right)$	$\tau = \frac{VQ}{Ib}$

3 Kuconcrete

3.1 Properties

- The **concrete compressive strength** f'_c and the **concrete tensile strength** f'_t is related by the relationship:

$$f'_t = 0.33\sqrt{f'_c} \quad (14)$$

- The Young's modulus of the concrete E_c can be correlated to the compressive strength of concrete via:

$$E_c = 4730\sqrt{f'_c} \quad (15)$$

- For *reinforcing steel*, the Young's modulus is $E_s = 200,000\text{MPa}$ and the yield strength is $f_y = 400\text{MPa}$.

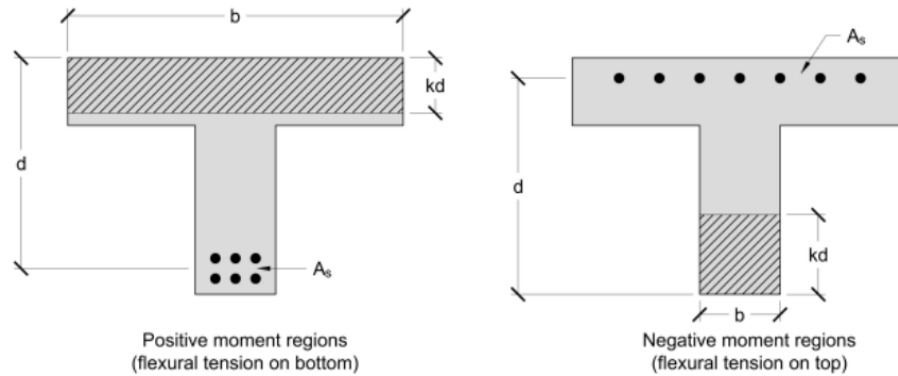
- The **modular ratio** n is given as:

$$n = \frac{E_s}{E_c} \quad (16)$$

- The **quantity of longitudinal reinforcement** ρ is given as:

$$\rho = \frac{A_s}{bd} \quad (17)$$

where A_s is the area of the steel reinforcements, b is the width of the cross sectional region of interest and d is the distance from the top/bottom edge of the region of interest to the opposing reinforcements. Refer to the below diagram:



- The value of k (scaling factor such that kd is the distance from the extreme compression fibre to the neutral axis) is given as:

$$k = \sqrt{(n\rho)^2 + 2n\rho} - n\rho \quad (18)$$

- The value of j (scaling factor such that the **flexural lever** jd is the vertical distance between the compressive and tensile forces) is given as:

$$j = 1 - \frac{1}{3}k \quad (19)$$

- If the values of k and j are unknown, let $k = \frac{3}{8}$ and $j = \frac{7}{8}$.

3.2 Flexural Stress Analysis

- The stress in the reinforcement f_s is given by:

$$f_s = \frac{M}{A_s j d} \quad (20)$$

where M is the bending moment carried by the member.

- The stress in the concrete f_c is given by:

$$f_c = \frac{k}{1 - k n A_s j d} M \quad (21)$$

- The maximum moment which can be carried by the member if it fails by yielding, M_{yield} is given by:

$$M_{\text{yield}} = A_s f_y j d \quad (22)$$

- Perform the following tests to see if the concrete is safe:

$$- A_s \geq \frac{M}{0.6 f_y j d}$$

$$- f_s \leq 0.6 f_y$$

$$- f_c \leq 0.5 f'_c$$

3.3 Shear Stress Analysis

- The maximum shear stress v we need to design for in a cracked concrete member occurs in its web, and is given by:

$$v = \frac{V}{b_w j d} \quad (23)$$

where b_w is the effective web width.

- The shear stress v_{\max} that causes buckling to take place from the diagonal compression is given by:

$$v_{\max} = 0.25 f'_c \quad (24)$$

- With no shear reinforcement:** The shear strength of the concrete without shear reinforcement is given by:

$$V_c = \frac{230 \sqrt{f'_c}}{1000 + 0.9d} b_w j d \quad (25)$$

- With shear reinforcement:** These are created with stirrups, and the shear strength in the concrete is given by:

$$V_c = 0.18 \sqrt{f'_c} b_w j d \quad (26)$$

This equation is valid if:

$$\frac{A_v f_y}{b_w s} \geq 0.06 \sqrt{f'_c} \quad (27)$$

where A_v is the effective area of the stirrups. See the below diagram for different configurations:

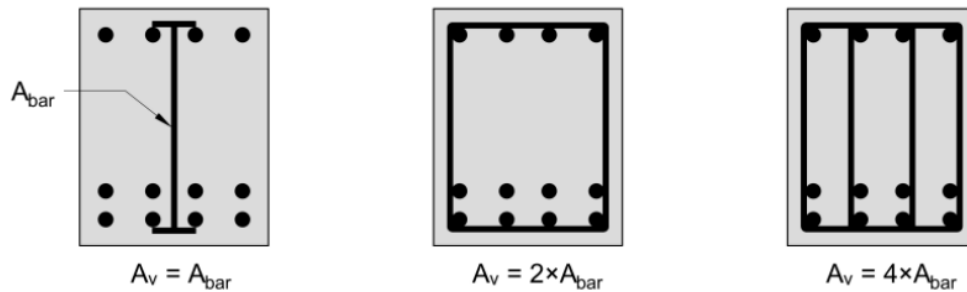


Fig 34.8 – Types of shear reinforcement and corresponding values of A_v

If this is not satisfied, we can calculate V_c using the equation with no shear reinforcements.

- If shear reinforcement is present, the maximum shear force carried in the truss is:

$$V_s = \frac{A_v f_y j d}{s} \cot(35^\circ) \quad (28)$$

where s is the spacing of the shear reinforcement.

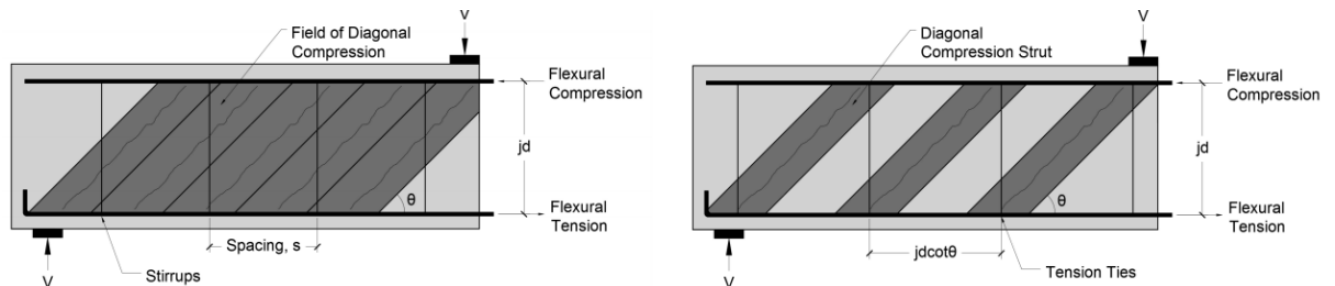


Fig. 34.9 – Diagonal stress fields in a cracked reinforced concrete beam (left) and Simplified truss model for concrete members subjected to shear (right)

- The **shear strength** V_r of the member is given by:

$$V_r = V_c + V_s \quad (29)$$

- The limit at which concrete crushes is:

$$V_{\max} = 0.25f'_c b_w j d \quad (30)$$

- The concrete will fail when:

$$V \geq \min\{V_r, V_{\max}\} \quad (31)$$

- For design, we want to pick V_r to satisfy:

$$V_r = 0.5V_c + 0.6V_s \leq 0.5V_{\max} \quad (32)$$

where the constants represent the factors of safety. If a given design is not safe, here are the things that can be tried:

- If $V \geq 0.5V_{\max}$, the cross section needs to be resized.
- If $V \geq 0.5V_c$, then reinforcements need to be made.
- If $V \geq 0.5V_c + 0.6V_s$, then the spacing needs to be changed to:

$$s = \frac{0.6A_v f_y j d \cot(\theta)}{V - 0.5 \times 0.18 \sqrt{f'_c} b_w j d} \quad (33)$$

Idea: In real life, cracks happen not at the highest shear, but instead a distance d away from it. Therefore, the maximum shear force we are designing for is given by:

$$V_{\text{design}} = V_{\text{support}} - wd \quad (34)$$

where w is the weight distribution. If $V_{\text{design}} \leq V_c$, no shear reinforcement is needed.

3.4 Prestressed Concrete

- The stress σ_c in prestressed concrete with concentric tendons is given by:

$$\sigma_{c,top} = -\frac{P}{A} - \frac{My_{top}}{I} \quad (35)$$

$$\sigma_{c,bot} = -\frac{P}{A} + \frac{My_{top}}{I} \quad (36)$$

- If the tendon was eccentric (offset from the center by a distance e), the stresses in the concrete are then:

$$\sigma_{c,top} = -\frac{P}{A} + \frac{Pe y_{top}}{I} - \frac{My_{top}}{I} \quad (37)$$

$$\sigma_{c,bot} = -\frac{P}{A} - \frac{Pe y_{top}}{I} + \frac{My_{top}}{I} \quad (38)$$