

PHY293: Tutorial Problems

Tutorial 1 Solutions

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1. (a) The angular frequency is

$$\omega = \sqrt{\frac{k}{m}} = 5 \text{ rad/s}$$

- (b) The total mechanical energy of the system is equal to the potential energy at maximum compression:

$$E = \frac{1}{2}kA^2 = 0.36 \text{ J}.$$

- (c) Using conservation of energy, we have

$$E = \frac{1}{2}mv^2 + \frac{1}{2}kx(0)^2.$$

We know everything except v , so solving for it gives $v = 0.566 \text{ m/s}$. We want velocity so the answer is

$$\vec{v} = 0.566 \text{ m/s [right]}.$$

- (d) We have $x(t) = A \sin(\omega t + \phi)$. Using the initial condition $x(0) = -0.04 \text{ m}$, we have $-0.333 = \sin(\phi)$. We get two solutions: $\phi = -19.47^\circ$ and $\phi = 199.5^\circ$. We want $v(0) = A\omega \cos(\phi) > 0$, so the right solution is $\phi = 19.47^\circ$.

- (e) The spring will reach equilibrium when $\sin(\omega t + \phi) = 0$, or when $\omega t + \phi = 0$. This occurs after a time

$$\Delta t = \frac{-\phi}{\omega} = 0.0680 \text{ s}.$$

Since the spring is symmetric across equilibrium, it takes another Δt seconds to reach $+0.040 \text{ m}$, so the time at which it first reaches here is

$$t_1 = 2\Delta t = 0.136 \text{ s}.$$

The period is $T = \frac{2\pi}{\omega} = 1.257 \text{ s}$, so the time at which the block reaches this location a second time (i.e. on the way back) is:

$$t_2 = T/2 = 0.628 \text{ s}.$$

2. The velocity function is given by $v(t) = A\omega \cos(\omega t + \phi)$. The maximum speed is $A\omega = 2 \text{ cm/s}$, and $v(0) = -1$, so we have $-1 = 2 \cos(\phi)$. Solving for ϕ gives $\phi = 120^\circ$ and $\phi = 240^\circ$.

The mass is travelling to the left and is about to reach maximum elongation, so the position $x(t) = A \sin(\phi)$ is negative. Therefore, we have $\phi = 240^\circ$.

3. **System 1:** The angular frequency is $\omega = \sqrt{\frac{k_a}{m}}$.

System 2: Suppose the block is moved a distance x from equilibrium. Then the equation of motion (from $F = ma$) is:

$$ma = -k_b x + (-k_b x) = -2k_b x.$$

Therefore, the effective spring constant is $2k_b$ and the angular frequency is $\omega = \sqrt{\frac{2k_b}{m}}$.

System 3: We claim that the effective spring constant is $\frac{k_c}{2}$. There are three ways to see this:

- *Method 1:* The springs are identical, so if one spring stretches by $\Delta x/2$, then the other spring will also stretch by $\Delta x/2$, resulting in a net stretch of Δx . Therefore, when the mass moves a distance x , it only experiences a force of $-k(x/2)$.
- *Method 2:* We can view this as one long spring. Recall from CIV102 that the spring constant is $k = \frac{EA}{L}$, where E is the Young's Modulus, A is the cross sectional area, and L is the length. We're not changing E or A , but by doubling L , we are halving k .
- *Method 3:* Let the mass move a distance d and let the spring attached to it get stretched a distance Δx_1 , and let the spring attached to the wall get stretched a distance Δx_2 . We want to relate Δx_1 and Δx_2 . From Newton's third law, we have

$$k_c \Delta x_1 = k_c \Delta x_2 \implies \Delta x_1 = \Delta x_2$$

and we can continue with the same argument as method 1. However, this is a bit more general and can be used when the spring constants are not equal.

The angular frequency is then $\omega = \sqrt{\frac{k_c}{2m}}$. These frequencies are all equal, so we have

$$\sqrt{\frac{k_a}{m}} = \sqrt{\frac{2k_b}{m}} = \sqrt{\frac{k_c}{2m}} \implies k_a = 2k_b = k_c/2$$

which leads to the desired ratio of

$$k_a : k_b : k_c = 1 : 1/2 : 2.$$

4. We can consider the forces acting on it. There is a gravitational force mg downwards and a normal force N upwards. The mass will loss contact with the platform when $N = 0$, i.e. when the acceleration of the block is g .

The platform moves with a position $y(t) = A \sin(\omega t)$ where $\omega = 2\pi f = 15.7$ rad/s. Then the acceleration is $a(t) = A\omega^2 \sin(\omega t)$ and reaches a maximum value of $A\omega^2$. This is equal to g when

$$A = g/\omega^2 = 0.04 \text{ m}.$$

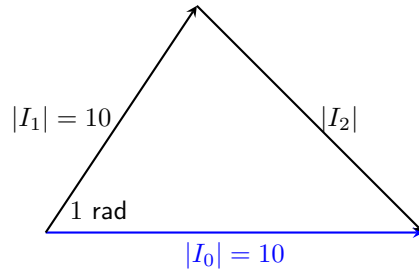
5. (a) We want to find an amplitude A such that

$$10 \cos(\omega t) = 10 \cos(\omega t + 1) + A \cos(\omega t + \phi), \quad (1)$$

or alternatively:

$$\begin{aligned} 10 \cos(\omega t) - 10 \cos(\omega t + 1) &= 10 (-2 \sin((\omega t + \omega t + 1)/2) \cos((\omega t - \omega t - 1)/2)) \\ &= -20 \sin(\omega t + 0.5) \sin(-1/2) \\ &= 9.59 \sin(\omega t + 0.5) \end{aligned}$$

where we used the difference in cosine formula. Therefore, the magnitude is $|I_2| = 9.59 \text{ A}$. There is actually a nice geometric interpretation of this using phasors. We want:



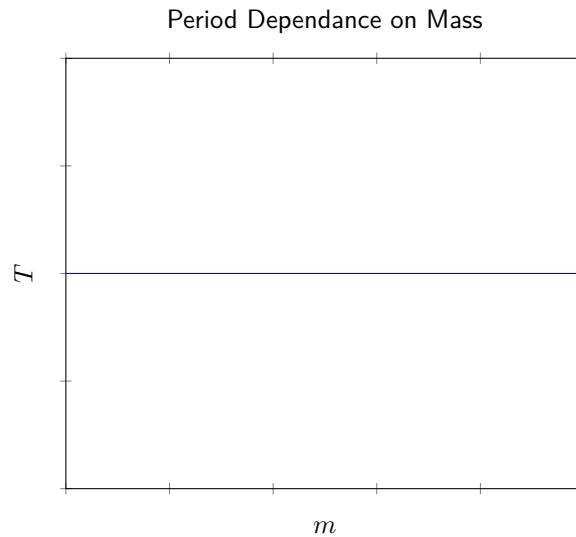
The sum of the two phasors $I_1 + I_2$ needs to be horizontal (which represents no phase shift), and we can determine this using cosine law:

$$|I_2| = \sqrt{10^2 + 10^2 - 2(10)(10)\cos(1)} = 9.59. \quad (2)$$

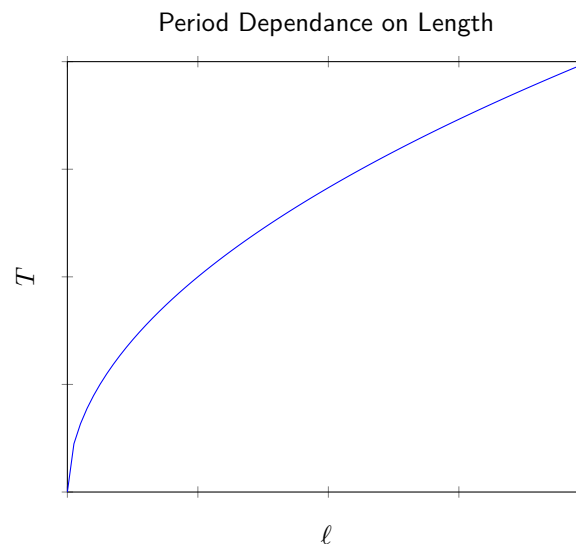
- (b) Using the same idea, note that the smallest $|I_2|$ such that the sum of the two phasors lie on the horizontal line is if I_2 is perpendicular to I_0 , in which we can use standard trigonometry:

$$I_2 = I_1 \sin(1) = 8.41 \text{ A}. \quad (3)$$

6. The period does not depend on the mass, so we have



The period depends on length as $T \propto \sqrt{\ell}$, so we have:



7. (a) Using trigonometry, we have

$$\theta = \sin^{-1} \left(\frac{0.0350}{0.750} \right) = 2.67^\circ \quad (4)$$

The small angle approximation can be used.

Note: To be more complete, using this θ results in approximately a 0.04% error. This is much less error than possible uncertainties in the length and position measurements.

(b) The initial height (measured from the top) is

$$h = \sqrt{0.750^2 - 0.0350^2} = 0.74918 \text{ m.} \quad (5)$$

so there is a height difference of $\Delta h = 0.000817 \text{ m}$ between the maximum and lowest point. Energy conservation tells us the maximum speed is

$$v = \sqrt{2g\Delta h} = 0.127 \text{ m/s.} \quad (6)$$

(c) This is a fourth of the period, so the time to reach this speed is

$$t = T/4 = \frac{1}{4} \cdot 2\pi \sqrt{\frac{\ell}{g}} = 0.434 \text{ s.} \quad (7)$$

8. (a) The relationship between a conservative force and potential energy is

$$F = -\frac{dU}{dx} \quad (8)$$

Applying this, we get

$$F = \frac{6a}{x^7} - \frac{12b}{x^{13}}. \quad (9)$$

(b) Equilibrium occurs when $F = 0$, or when:

$$\frac{6a}{x^7} = \frac{12b}{x^{13}} \implies x_0 = \left(\frac{2b}{a} \right)^{1/6}. \quad (10)$$

(c) The angular frequency at equilibrium is equal to

$$\omega = \sqrt{\frac{U''(x)}{m}} = \sqrt{\frac{F'(x)}{m}}. \quad (11)$$

Taking the derivative again, we get

$$F'(x) = -\frac{6a}{x^7} \frac{7}{x} + \frac{12b}{x^{13}} \frac{13}{x}. \quad (12)$$

Letting $\frac{6a}{x^7} = \frac{12b}{x^{13}}$, we have:

$$\begin{aligned} F'(x_0) &= -\frac{6a}{x_0^7} \frac{7}{x_0} + \frac{6a}{x_0^7} \frac{13}{x_0} \\ &= \frac{6a}{x_0^6} \left(\frac{13}{x_0^2} - \frac{7}{x_0^2} \right) \\ &= \frac{6a}{x_0^6} \left(\frac{6}{x_0^2} \right) \end{aligned}$$

Letting $x_0 = \left(\frac{2b}{a} \right)^{1/6}$ and substituting this in, we have

$$F'(x_0) = 36a \frac{a}{2b} \left(\frac{a}{2b} \right)^{1/3} = 36a \left(\frac{a}{2b} \right)^{4/3}. \quad (13)$$